Owing to the concentration of people, industries, and services, urbanized areas tend to be places of rather sharp environmental conflicts that directly involve a significant part of the planet's population -- city dwellers. As a result, nowadays city governments have to consider environmental factors in almost every planning or administrative decision. To do it efficiently they need a quick access to various data on the urban physical (natural) environment, including spatial ones. This requires, on the one hand, an adequate technology to store, process, and retrieve the above mentioned data; on the other hand, a reliable methodology for the collection, analysis and synthesis of environmental information.

The first part of the problem has been successfully solved by the application of computer technologies, particularly GIS. The solution of the second task tends to lag behind -- new powerful analytical tools put forward higher demands for the accuracy, integrity and compatibility of data, but traditional environmental information on separate land features, such as geomorphology, geology, potential vegetation, etc., in many cases fails to satisfy the new standards. The “feature” maps that are mostly compiled in various scales and on different methodological principles produce big spatial errors in multiple overlays (e.g., Berry, 1994), and sometimes have logically unmatchable structures of attribute information.

Landscape ecology, or landscape science as it is traditionally called in Eastern Europe, offers an integrated view of the geographic physical environment as a holistic spatial-temporal entity -- the landscape. It possesses concrete methods, including cartographic ones, for the inventory and assessment of the latter (e.g., Isachenko, 1973, 1980; Zonneveld and Forman, 1990; Haase, 1991). Therefore, introduction of landscape-ecological principles into the practice of applied environmental studies, especially in such a complex primary-anthropogenic formation as urban areas, is an effective way to overcome the difficulty. Thus, a landscape-ecological information system is a result of the integration of landscape-ecological methodology and GIS technology.

The above mentioned idea forms the methodological basis of a pilot project being carried out at the Department of Physical Geography, Lviv State University. At the moment, a landscape-ecological data base has been created for the Lviv downtown and some environmental models developed using ARC/INFO and ERDAS software. The landscape-ecological data utilized in the GIS were obtained through the special interpretation of the previously available materials as well as additional studies in situ (Krouglov, 1992).

According to the historical-genetic approach the urban landscape is presented as a spatial-temporal combination of two geographic subsystems -- the primary basis and the anthropogenic cover. The first one includes the remains of the landscape’s primary features formed before the interference of man. The second one consists of those material components of the urban area, which have been created by the human activities. A special study allows to determine probable character of the destroyed or significantly altered primary geocomponents, such as vegetation and soil cover (Krouglov and Miller, 1993).

In accordance with this notion, the core of the primary landscape-ecological data base consists of only two polygon coverages corresponding to the above mentioned urban landscape’s subsystems. The polygon attribute tables (PATs) contain diverse environmental information that can be represented by choropleth maps (Fig. 1). The overlay of the two coverages conveys complete physical heterogeneity of the area and can be used as the basis for further geographic modeling. Since the coverages are digitized from maps compiled under the same methodology and at the same scale, they ensure much smaller spatial error propagation when overlaid than separate “feature” maps. The
other advantage is absolute logical compatibility of the attribute information and more effective use of computer resources.

**Primary Basis**

*Attribute data:*
- Landforms’ genetic type
- Slope - min, max, avg (%)
- Relative height - min, max (m)
- Quaternary deposits’ genesis
- Quaternary deposits’ age
- Quaternary deposits’ texture
- Quat. deposits’ thickness - min, max (m)
- Bedrock age
- Bedrock lithology

*Probable characteristics of destroyed or significantly altered primary components*
- Ground water level - min, max (m)
- Habitat type
- Soil genetic (sub)type
- Forest type

**Technogenic Cover**

*Attribute data:*
- Type of architectural structure
- Open ground ratio - min, max (%)
- Built-up ratio - min, max (%)
- Building height - avg (storeys)

*Figure 1. The structure of the primary landscape-ecological data base.*

The primary data base also includes the transportation network coverages and a multispectral satellite image. It is planned to supplement it with a contour map/DEM, point sources of air and ground or surface water pollution, catchment boundaries, and some other features that convey the structure of the urban physical environment (see Fig. 1).

In many cases environmental data should be referenced to the social-geographic entities, such as city or administrative district limits, parcel boundaries, or zoning codes. Therefore, the landscape-ecological data base has to be linked to the municipal GIS.

The **derivative landscape-ecological data base** contains geographic information obtained from the primary data base through queries and modeling. The overlaid landscape coverages allow one to make operative complex spatial queries, such as allocation (*e.g.*, for construction purposes) of the non-built or sparsely built terrain with low surface gradients and favorable geological conditions.
Supplemented with the transportation network data, the query can be elaborated by the economic location conditions (e.g., the site should be within 100 m from a main street), etc.

Environmental information of a rather high level of integration can be derived from the primary database with the help of a special landscape-ecological modeling. Since the procedure of the environmental assessment of residential areas in Lviv is discussed elsewhere (Krouglov, 1997), in this paper estimation of the integral technogenic transformation of the primary environment will be considered below.

The landscape-ecological approach offers an opportunity, on the one hand, to trace technogenic changes in separate primary features of the environment (analytical approach), and, on the other hand, to estimate the integral transformation of the whole primary landscape (synthetic approach). This estimation is based on the notion that the extent and the character of the environmental change depend both on the magnitude and peculiarities of the technogenic load as well as on the inherent stability of the primary landscape withstanding this load. Therefore, data from both landscape coverages are used as input into the model. The latter can be applied both for the description of the already built-up patches as well as for the prediction of the environmental changes in the area of a future urban development. It is based on the principle of evaluation classification (Isachenko, 1980), and accepts input data in their natural expression, both quantitative and qualitative.

The process of modeling includes several steps. The purpose of the first step is to select evaluation indices. The built-up ratio of the technogenic cover is adopted as a characteristic that reflects the magnitude of the technogenic load on the primary environment. The texture of the surface geological deposits and the slope are taken as properties that indicate the stability of the terrain to the building load. The sites of the profound technogenic transformation such as quarries and big mounds are considered separately (Krouglov and Miller, 1993).

The second step consists of setting the evaluation intervals and hierarchical ranks for the chosen indices. The results are shown in the table.

**Table.** The evaluation indices for the estimation of the environmental transformation

<table>
<thead>
<tr>
<th>Hier. rank</th>
<th>Index name</th>
<th>Measur. unit</th>
<th>“Weakest”</th>
<th>“Strongest”</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Built-up ratio (max.)</td>
<td>%</td>
<td>&lt;= 15</td>
<td>&gt; 15 and &lt;= 25</td>
</tr>
<tr>
<td>2</td>
<td>Quaternary deposits’ texture</td>
<td>None</td>
<td>Sand, loamy sand, loam</td>
<td>Mud, peat</td>
</tr>
<tr>
<td>3</td>
<td>Slope (avg.)</td>
<td>%</td>
<td>&lt;= 10</td>
<td>&gt; 10 and &lt;= 20</td>
</tr>
</tbody>
</table>

If the operations in the first two procedures are conducted interactively by the expert in landscape ecology, the subsequent steps are a routine job that can be done in a batch mode. At the beginning, an overlay of the two coverages is made and a new polygon topology is established. Then, an additional item that will contain the results of the evaluation classification is created in the PAT of the newly synthesized coverage. After this, the operations with the attribute data begin.

At first, the evaluation matrix is built. The number of the matrix’s dimensions is defined by the count of evaluation indices. For example, in the case considered, a 3D matrix is formed, because three evaluation indices (see Table) are used. The count of intervals of an evaluation index determines the number of divisions for the respective dimension. Therefore, the total of the matrix’s cells is equal to the number of intervals per index, multiplied by each other. In our case the quantity of matrix cells is 3 * 2 * 3 = 18. Not all the cells of the matrix may be filled in, because some combinations of characteristics used in evaluation may not take place in reality. In the Lviv downtown 11 combinations out of the 18 theoretically possible are observed. Each dimension has a hierarchical order that is the same as a hierarchical rank of the respective evaluation index. The dimensions (and evaluation indices respectively) must not have same hierarchical order.

The next operation is the transformation of a multidimensional matrix into a one-dimensional array. The latter has to convey the sequence of classes of the phenomenon under evaluation, ordered from the “weakest” (“worst”) to the “strongest” (“best”), or vice versa. The array is formed through the sequential entering of the matrix’s elements according to the hierarchy of dimensions. Each
classification unit receives the value according to the position in the array. The values are written into the specially prepared column of the PAT.

After the evaluation classification is made, the final step is to make the synthesized coverage cartographically correct. The boundaries between the polygons with the same values of environmental transformation are dissolved; and sliver polygons are eliminated using thresholds on area and perimeter/area ratio.

The resulting map (Fig. 2) reflects the integral transformation of the natural environment.

![Figure 2. The integral transformation of the natural environment. (The values of transformation are from the “weakest” (1) to the “strongest” (12).)](image)

**References**


